# Universal High Brightness LED Driver

#### **Features**

- ▶ >90% Efficiency
- 8V to 450V input range
- Constant-current LED driver
- Applications from a few mA to more than 1A Output
- ▶ LED string from one to hundreds of diodes
- ► PWM Low-Frequency Dimming via Enable pin
- Input Voltage Surge ratings up to 450V

## **Applications**

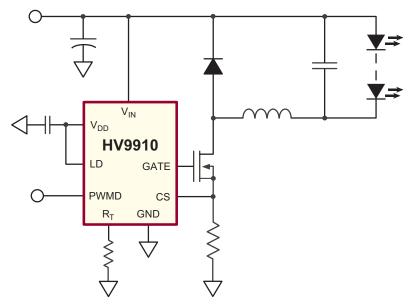
- ▶ DC/DC or AC/DC LED Driver applications
- RGB Backlighting LED Driver
- Back Lighting of Flat Panel Displays
- General purpose constant current source
- Signage and Decorative LED Lighting
- Automotive
- Chargers

#### **General Description**

The HV9910 is a PWM high-efficiency LED driver control IC. It allows efficient operation of High Brightness (HB) LEDs from voltage sources ranging from 8VDC up to 450VDC. The HV9910 controls an external MOSFET at fixed switching frequency up to 300kHz. The frequency can be programmed using a single resistor. The LED string is driven at constant current rather than constant voltage, thus providing constant light output and enhanced reliability. The output current can be programmed between a few milliamps and up to more than 1.0A.

The HV9910 uses a rugged high voltage junction isolated process that can withstand an input voltage surge of up to 450V. Output current to an LED string can be programmed to any value between zero and its maximum value by applying an external control voltage at the linear dimming control input of the HV9910. The HV9910 provides a low-frequency PWM dimming input that can accept an external control signal with a duty ratio of 0-100% and a frequency of up to a few kilohertz.

# **Typical Application**



# **Ordering Information**

Dovice	Package Options					
Device	SOIC-16	SOIC-8				
HV9910	HV9910NG-G	HV9910LG-G				

<sup>-</sup>G indicates package is RoHS compliant ('Green')

## **Absolute Maximum Ratings**

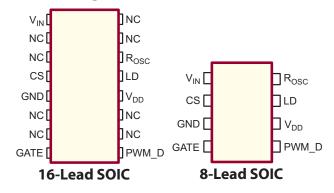
Parameter	Value			
V <sub>IN</sub> to GND	-0.5V to +470V			
CS	-0.3V to (V <sub>DD</sub> + 0.3V)			
LD, PWM_D to GND	-0.3V to (V <sub>DD</sub> - 0.3V)			
GATE to GND	-0.3V to (V <sub>DD</sub> + 0.3V)			
V <sub>DDMAX</sub>	13.5V			
Continuous Power Dissipation (T <sub>A</sub> = +25°C) (Note 1)				
16-Pin SO (derate 7.5mW/°C above +25°C)	750mW			
8-Pin SO (derate 6.3mW/°C above +25°C)	630mW			
Operating temperature range	-40°C to +85°C			
Junction temperature	+125°C			
Storage temperature range	-65°C to +150°C			

Absolute Maximum Ratings are those values beyond which damage to the device may occur. Functional operation under these conditions is not implied. Continuous operation of the device at the absolute rating level may affect device reliability. All voltages are referenced to device ground.

# (%)



# **Pin Configurations**



#### **Electrical Characteristics**

(Over recommended operating conditions unless otherwise specified -  $T_A$  = 25°C)

Symbol	Parameter	Min	Тур	Max	Units	Conditions
V <sub>INDC</sub>	Input DC supply voltage range	8.0		450	V	DC input voltage
I <sub>INsd</sub>	Shut-down mode supply current	-	0.5	1	mA	Pin PWM_D to GND, V <sub>IN</sub> = 8V
V <sub>DD</sub>	Internally regulated voltage	7.0	7.5	8.0	V	$V_{IN} = 8 - 450V$ , $I_{DD(ext)} = 0$ , pin GATE open
$V_{\scriptscriptstyle DDmax}$	Maximal pin V <sub>DD</sub> voltage	-	-	13.5	V	When an external voltage applied to pin $V_{\scriptscriptstyle DD}$
I <sub>DD(ext)</sub>	V <sub>DD</sub> current available for external circuitry <sup>1</sup>	-	-	1.0	mA	V <sub>IN</sub> = 8 – 100V
UVLO	V <sub>DD</sub> undervoltage lockout threshold	6.45	6.7	6.95	V	V <sub>IN</sub> rising
ΔUVLO	V <sub>DD</sub> undervoltage lockout hysteresis	-	500	-	mV	V <sub>IN</sub> falling
V <sub>EN(Io)</sub>	Pin PWM_D input low voltage	-	-	1.0	V	V <sub>IN</sub> = 8 – 450V
V <sub>EN(hi)</sub>	Pin PWM_D input high voltage	2.4	-	-	V	V <sub>IN</sub> = 8 – 450V
R <sub>EN</sub>	Pin PWM_D pull-down resistance	50	100	150	kΩ	V <sub>EN</sub> = 5V
V <sub>CS(hi)</sub>	Current sense pull-in threshold voltage	225	250	275	mV	@T <sub>A</sub> = -40°C to +85°C
V <sub>GATE(hi)</sub>	GATE high output voltage	V <sub>DD</sub> -0.3	-	$V_{_{DD}}$	V	I <sub>OUT</sub> = 10mA
V <sub>GATE(Io)</sub>	GATE low output voltage	0	-	0.3	V	I <sub>OUT</sub> = -10mA
f <sub>osc</sub>	Oscillator frequency	20 80	25 100	30 120	kHz kHz	$R_T = 1.00M\Omega$ $R_T = 226k\Omega$
D <sub>MAXhf</sub>	Maximum PWM duty cycle	-	-	100	%	F <sub>PWMhf</sub> = 25kHz, at GATE, CS to GND.
V <sub>LD</sub>	Linear dimming pin voltage range	0	-	250	mV	@T <sub>A</sub> = <85°C, V <sub>IN</sub> = 12V
T <sub>BLANK</sub>	Current sense blanking interval	150	215	280	ns	$V_{CS} = 0.55V_{LD}, V_{LD} = V_{DD}$

<sup>&</sup>lt;sup>1</sup> Also limited by package power dissipation limit, whichever is lower.

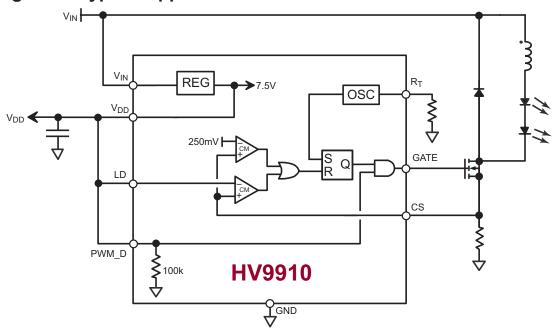
Symbol	Parameter	Min	Тур	Max	Units	Conditions
t <sub>DELAY</sub>	Delay from CS trip to GATE lo	-	-	300	ns	$V_{IN} = 12V, V_{LD} = 0.15,$ $V_{CS} = 0 \text{ to } 0.22V \text{ after } T_{BLANK}$
t <sub>RISE</sub>	GATE output rise time	-	30	50	ns	C <sub>GATE</sub> = 500pF
t <sub>FALL</sub>	GATE output fall time	-	30	50	ns	C <sub>GATE</sub> = 500pF

# **Pinout**

Pin	SOIC-16	SOIC-8	Description
V <sub>IN</sub>	1	1	Input voltage 8V to 450V DC
CS	4	2	Senses LED string current
GND	5	3	Device ground
GATE	8	4	Drives the gate of the external MOSFET
PWM_D	9	5	Low Frequency PWM Dimming pin, also Enable input. Internal $100 k\Omega$ pull-down to GND
V <sub>DD</sub>	12	6	Internally regulated supply voltage (7.5V nominal). Can supply up to 1mA for external circuitry. A sufficient storage capacitor is used to provide storage when the rectified AC input is near the zero crossings.
LD	13	7	Linear dimming by changing the current limit threshold at current sense comparator
$R_{\scriptscriptstyle T}$	14	8	Oscillator control. A resistor connected between this pin and ground sets the PWM frequency.

No Connects (NC) are not internally connected and may be used for pass-thru PCB traces.

# **Block Diagram & Typical Applications**



## **Application Information**

#### **AC/DC Off-Line Applications**

The HV9910 is a low-cost off-line buck or boost converter control IC specifically designed for driving multi-LED stings or arrays. It can be operated from either universal AC line or any DC voltage between 8-450V. Optionally, a passive power factor correction circuit can be used in order to pass the AC harmonic limits set by EN 61000-3-2 Class C for lighting equipment having input power less than 25W. The HV9910 can drive up to hundreds of High-Brightness (HB) LEDs or multiple strings of HB LEDs. The LED arrays can be configured as a series or series/parallel connection. The HV9910 regulates constant current that ensures controlled brightness and spectrum of the LEDs, and extends their lifetime. The HV9910 features an enable pin (PWM\_D) that allows PWM control of brightness.

The HV9910 can also control brightness of LEDs by programming continuous output current of the LED driver (so-called linear dimming) when a control voltage is applied to the LD pin.

The HV9910 is offered in a standard 8-pin SOIC package. It is also available in a high voltage rated SO-16 package for applications that require  $V_{\rm IN}$  greater than 250V.

The HV9910 includes an internal high-voltage linear regulator that powers all internal circuits and can also serve as a bias supply for low voltage external circuitry.

#### **LED Driver Operation**

The HV9910 can control all basic types of converters, isolated or non-isolated, operating in continuous or discontinuous conduction mode. When the gate signal enhances the external power MOSFET, the LED driver stores the input energy in an inductor or in the primary inductance of a transformer and, depending on the converter type, may partially deliver the energy directly to LEDs The energy stored in the magnetic component is further delivered to the output during the offcycle of the power MOSFET producing current through the string of LEDs (Flyback mode of operation).

When the voltage at the  $V_{DD}$  pin exceeds the UVLO threshold the gate drive is enabled. The output current is controlled by means of limiting peak current in the external power MOSFET. A current sense resistor is connected in series with the source terminal of the MOSFET. The voltage from the sense resistor is applied to the CS pin of the HV9910. When the voltage at CS pin exceeds a peak current sense voltage threshold, the gate drive signal terminates, and the power MOSFET turns off. The threshold is internally set to 250mV, or it can be programmed externally by applying

voltage to the LD pin. When soft start is required, a capacitor can be connected to the LD pin to allow this voltage to ramp at a desired rate, therefore, assuring that output current of the LED ramps gradually.

Optionally, a simple passive power factor correction circuit, consisting of 3 diodes and 2 capacitors, can be added as shown in the typical application circuit diagram of Figure 1.

#### **Supply Current**

A current of 1mA is needed to start the HV9910. As shown in the block diagram on page 3, this current is internally generated in the HV9910 without using bulky startup resistors typically required in the offline applications. Moreover, in many applications the HV9910 can be continuously powered using its internal linear regulator that provides a regulated voltage of 7.5V for all internal circuits.

#### **Setting Light Output**

When the buck converter topology of Figure 2 is selected, the peak CS voltage is a good representation of the average current in the LED. However, there is a certain error associated with this current sensing method that needs to be accounted for. This error is introduced by the difference between the peak and the average current in the inductor. For example if the peak-to-peak ripple current in the inductor is 150mA, to get a 500mA LED current, the sense resistor should be  $250\text{mV}/(500\text{mA} + 0.5*150\text{mA}) = 0.43\Omega$ .

#### Dimming

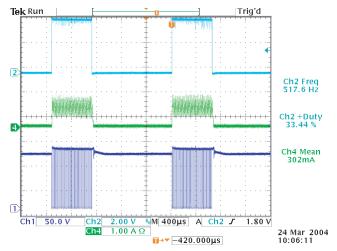
Dimming can be accomplished in two ways, separately or combined, depending on the application. Light output of the LED can be controlled either by linear change of its current, or by switching the current on and off while maintaining it constant. The second dimming method (so-called PWM dimming) controls the LED brightness by varying the duty ratio of the output current.

The linear dimming can be implemented by applying a control voltage from 0 to 250mV to the LD pin. This control voltage overrides the internally set 250mV threshold level of the CS pin and programs the output current accordingly. For example, a potentiometer connected between  $V_{\rm DD}$  and ground can program the control voltage at the CS pin. Applying a control voltage higher than 250mV will not change the output current setting. When higher current is desired, select a smaller sense resistor.

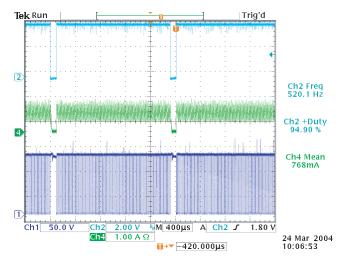
The PWM dimming scheme can be implemented by applying an external PWM signal to the PWM\_D pin. The PWM signal

can be generated by a microcontroller or a pulse generator with a duty cycle proportional to the amount of desired light output. This signal enables and disables the converter modulating the LED current in the PWM fashion. In this mode, LED current can be in one of the two states: zero or the nominal current set by the current sense resistor. It is not possible to use this method to achieve average brightness levels higher than the one set by the current sense threshold level of the HV9910. By using the PWM control method of the HV9910, the light output can be adjusted between zero and 100%. The accuracy of the PWM dimming method is limited only by the minimum gate pulse width, which is a fraction of a percent of the low frequency duty cycle.

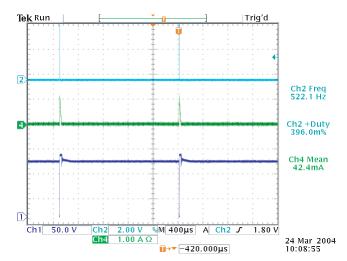
Some of the typical waveforms illustrating the PWM dimming method used with the application circuit on page 7 are given below.  $CH_1$  shows the MOSFET Drain voltage,  $CH_2$  is the PWM signal to pin PWM\_D and  $CH_4$  is the current in the LED string.



33% PWM Ratio at 500Hz Dimming



95% PWM Ratio at 500Hz Dimming



0.4% PWM Ratio at 500Hz Dimming

#### **Programming Operating Frequency**

The operating frequency of the oscillator is programmed between 25 and 300kHz using an external resistor connected to the  $R_{\tau}$  pin:

 $F_{OSC} = 25000/(R_{T} [k\Omega] + 22) [kHz]$ 

#### **Power Factor Correction**

When the input power to the LED driver does not exceed 25W, a simple passive power factor correction circuit can be added to the HV9910 typical application circuit on page 7 in order to pass the AC line harmonic limits of the EN61000-3-2 standard for Class C equipment. The typical application circuit diagram shows how this can be done without affecting the rest of the circuit significantly. A simple circuit consisting of 3 diodes and 2 capacitors is added across the rectified AC line input to improve the line current harmonic distortion and to achieve a power factor greater than 0.85.

#### **Inductor Design**

Referring to the typical application circuit on page 7 the value can be calculated from the desired peak-to-peak LED ripple current in the inductor. Typically, such ripple current is selected to be 30% of the nominal LED current. In the example given here, the nominal current  $I_{\rm LED}$  is 350mA.

The next step is determining the total voltage drop across the LED string. For example, when the string consists of 10 High-Brightness LEDs and each diode has a forward voltage drop of 3.0V at its nominal current; the total LED voltage  $V_{\rm LEDS}$  is 30V.

Knowing the nominal rectified input voltage  $V_{IN} = 120V^*1.41$  = 169V, the switching duty ratio can be determined, as:

$$D = V_{IEDs} / V_{IN} = 30/169 = 0.177$$

Then, given the switching frequency, in this example  $f_{\rm OSC}$  = 50KHz, the required on-time of the MOSFET transistor can be calculated:

$$T_{ON} = D/f_{OSC} = 3.5$$
 microsecond

The required value of the inductor is given by:

$$L = (V_{IN} - V_{LEDs}) * T_{ON}/(0.3 * I_{LED}) = 4.6 mH$$

#### **Input Bulk Capacitor**

An input filter capacitor should be designed to hold the rectified AC voltage above twice the LED string voltage throughout the AC line cycle. Assuming 15% relative voltage ripple across the capacitor, a simplified formula for the minimum value of the bulk input capacitor is given by:

$$C_{MIN} = I_{LED}^* V_{LEDs}^* 0.06 / V_{IN}^2$$

 $C_{MIN}$  = 22  $\mu$ F, a value 22 $\mu$ F/250V can be used.

A passive PFC circuit at the input requires using two series connected capacitors at the place of calculated  $C_{\text{min}}$ . Each of these identical capacitors should be rated for ½ of the input voltage and have twice as much capacitance.

#### **Enable**

The HV9910 can be turned off by pulling the PWM\_D pin to ground. When disabled, the HV9910 draws quiescent current of less than 1mA.

#### **Output Open Circuit Protection**

When the buck topology is used, and the LED is connected in series with the inductor, there is no need for any protection against an open circuit condition in the LED string. Open LED connection means no switching and can be continuous.

## DC/DC Low Voltage Applications

#### **Buck Converter Operation**

The buck power conversion topology can be used when the LED string voltage is needed to be lower than the input supply voltage. The design procedure for a buck LED driver outlined in the previous chapters can be applied to the low voltage LED drivers as well. However, the designer must keep in mind that the input voltage must be maintained higher than 2 times the forward voltage drop across the LEDs. This limitation is related to the output current instability that may develop when the HV9910 buck converter operates at a duty cycle greater than 0.5. This instability reveals itself as an oscillation of the output current at a sub-harmonic of the switching frequency.

**Figure 1: Typical Application Circuit** 

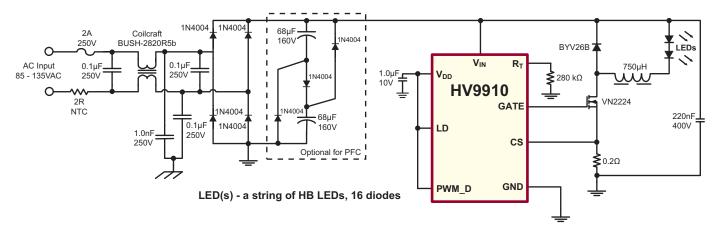
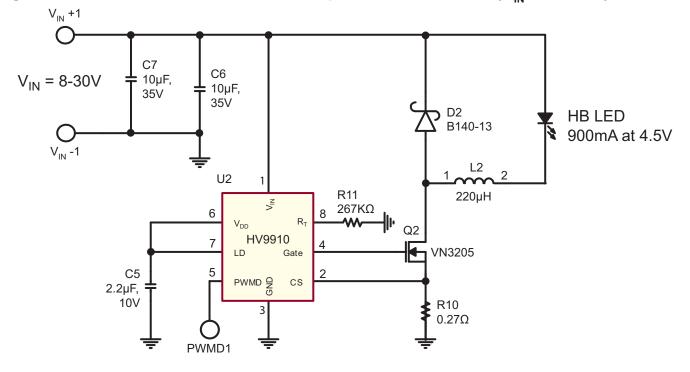
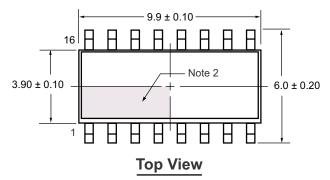


Figure 2: HV9910 Buck driver for a simple 900mA HB LED ( $V_{IN}$  = 8 - 30V)

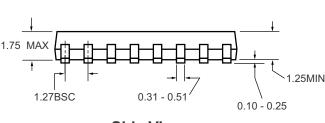


## 16-Lead SOIC (NG) Package Outline

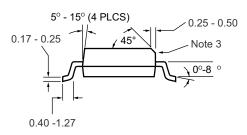


#### Notes:

- 1. All dimensions in millimeters; angles in degrees
- 2. Pin 1 identifier must be located within the indicated area
- 3. Corner shape may differ from drawing

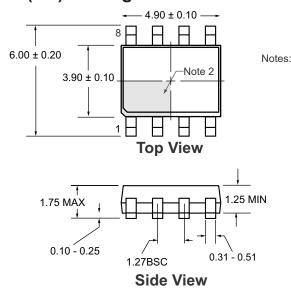


**Side View** 



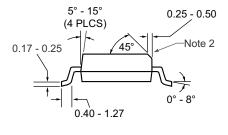
**End View** 

## 8-Lead SOIC (LG) Package Outline



#### :

- 1. All dimensions in millimeters. Angles in degrees.
- If the corner is not chamfered, then a Pin 1 identifier must be located within the area indicated.



**End View** 

(The package drawings in this data sheet may not reflect the most current specifications. For the latest package outline information go to <a href="http://www.supertex.com/packaging.html">http://www.supertex.com/packaging.html</a>.)

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